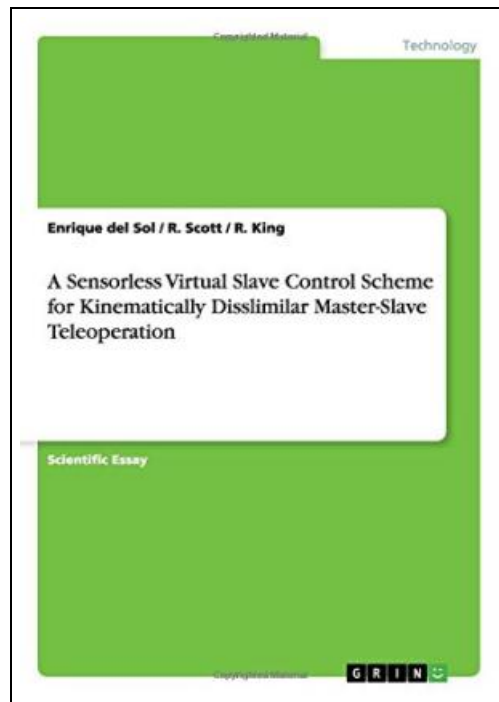


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A SENSORLESS VIRTUAL SLAVE CONTROL SCHEME FOR KINEMATICALLY DISSLIMILAR MASTER-SLAVE TELEOPERATION

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