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MODELING AND SIMULATION OF UNDERWATER FLEXIBLE ROBOT



Modeling and Simulation of Underwater Flexible Robot



Condition: New. Publisher/Verlag: LAP Lambert Academic Publishing | Seventy percent of the earth is surrounded by water and there may be lots of raw material still unexplored. A human being cannot dive longer because breathing could be one of the major constraints. For the deep-sea applications like debris removal, pipeline inspection, surveys, telecommunications support, research, maintenance, there must be need of some technology which can venture down without any constraints. Underwater robots technology is the best solution to this because...

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