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Condition: New. Publisher/Verlag: LAP Lambert Academic Publishing | Design and Implementation for On-Line Compensation of Nonlinearities | PID Controllers are the most common controller in industrial applications. Their main disadvantage is their loss of performance when the process under control modifies its behavior due to aging or change in operating conditions (raw materials, equipment, operators). This book presents two design alternatives of supervision techniques to online change the PID controller tuning parameters to improve the control loop performance. Since...

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